

SESSION 19 – TAPA III  
Sensor Microsystems

Friday, June 18, 3:25 p.m.

Chairpersons: T. Blalock, University of Virginia  
M. Ikeda, University of Tokyo

**19.1 — 3:25 p.m.**

**A Pixel-Level Color Image Sensor With Efficient Ambient Light Suppression Using Modulated RGB Flashlight and Application to TOF Range Finding**, Y. Oike, M. Ikeda and K. Asada, University of Tokyo, Tokyo, Japan

We present a pixel-level color image sensor with efficient ambient light suppression using a modulated RGB flashlight to support a recognition system. Bidirectional photo integrators realize in-pixel demodulation of a projected flashlight with suppressing an ambient light at short intervals during exposure time to avoid saturation from ambient illumination. Every pixel has a capability of depth and color capture. A prototype chip has been designed using 0.35  $\mu\text{m}$  CMOS process and successfully tested.

**19.2 — 3:50 p.m.**

**A Micro-Sized Photo Detectable Stimulator Array for Retinal Prosthesis by Distributed Sensor Network Approach**, A. Uehara, Y.-L. Pan, K. Kagawa, T. Tokuda, J. Ohta and M. Nunoshita, Nara Institute of Science and Technology, Nara, Japan

In this paper, we propose a flexible retinal prosthesis device by a distributed sensor network approach. The novel point of the proposed device is that the flexible stimulator consists of micro-sized CMOS devices linked in network. The micro-sized CMOS device consists of single-wire serial interface, a photodetector, an image processing circuit, and a current stimulator. The device is fabricated in a 0.6 $\mu\text{m}$  CMOS technology. The function of the prototype device is tested successfully.

**19.3 — 4:15 p.m.**

**CMOS Monolithic Atomic Force Microscope**, D. Barrettino, S. Hafizovic, T. Volden, J. Sedivy, K. Kirstein, A. Hierlemann and H. Baltes, Swiss Federal Institute of Technology, Zurich, Switzerland

A single-chip atomic force microscope fabricated in industrial CMOS-technology with post-CMOS micromachining is presented, which comprises an array of twelve cantilevers with integrated deflection sensors and actuators, digital proportional-integral-derivative (PID) deflection controllers, amplification stages, offset compensation circuitry, digital filters for sensor-actuator coupling compensation, A/D and D/A converters, dedicated serial lines (one per cantilever) for fast data transfer, and an I<sup>2</sup>C serial interface for chip programming. Parallel scanning imaging evidenced a height resolution better than 10nm

**19.4 — 4:40 p.m.**

**A New Input Switching Scheme for a Capacitive Micro-G Accelerometer**, B.V. Amini, S. Pourkamali, M. Zaman and F. Ayazi, Georgia Institute of Technology, Atlanta, GA

The design and implementation of a new input switching capacitive microaccelerometer interface circuit is presented. The accelerometers were fabricated on 50 $\mu\text{m}$  thick silicon-on-insulator (SOI) substrates using a two-mask, dry-release process and were interfaced with a new architecture switched-capacitor integrated circuit in a 0.25 $\mu\text{m}$  N-well CMOS process with a chip size of 0.65 $\text{mm}^2$ . The measured sensitivity is 0.45V/g and the output noise floor is 4.4 $\mu\text{g}/\text{rtHz}$  at 150Hz. The total power consumption is 5mW.

**19.5 — 5:05 p.m.**

**A 2.2- $\text{mm}^2$  CMOS Bioassay Chip and Wireless Interface**, T.S. Aytur, T. Ishikawa and B.E. Boser, Berkeley Sensor and Actuator Center, Berkeley, CA

A biological sensor and wireless interface have been implemented in a 0.25- $\mu\text{m}$  RF CMOS process. The device provides a bioassay platform based on an array of CMOS Hall-Effect sensors. The 2.2- $\text{mm}^2$  chip is powered and interrogated by a wireless link and requires no additional packaging for use in biological fluids.